

# USB Interface for KJ8916 Robotic Arm

The provided CD Contains main software manual from supplier on how to use the program. The program has two modes; BASIC and PROGRAM

Basic mode lets you control the robotic arm manually and is useful in testing and moving the joints independently.

Program mode lets you write a series of instructions to control the movement.

Please consult the manual on the disk for any further instructions needed.

## To install in any version of windows up to Windows 10:

1. Insert disk
2. Run "install.exe" in the "Robotic Arm" folder of the CD.
3. Install as normal.

## To install in Windows 10:

1. Insert disk
2. Right-click "install.exe" in the Robotic Arm folder of the CD
3. Click properties
4. Click the "Compatability" tab.
5. Click "Change settings for all users"
6. Change to Compatibility mode: "Windows XP Service Pack 3"
7. Tick the check box that says "Run as Administrator"
8. Click ok, save, and finish, to get out of the properties dialog.
9. Run the installer as normal by double clicking the Install.exe

If there is issues in connecting, make sure that you are running the software as administrator. You can do this by right-clicking the icon and selecting "Run as Administrator"